## Ergodic Theory - Week 7

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## Classifying measure preserving systems 1

P1. Show that any factor of an ergodic system is ergodic. Find an example of a non-ergodic system with an ergodic factor.

Let  $(X, \mathcal{A}, \mu, T)$  be an ergodic measure preserving system, let  $Y, \mathcal{B}, \nu, S$  be a factor, and let  $\pi: X \to Y$  be the associated factor map. Let f be a S-invariant function. Then we have that

$$f \circ \pi = f \circ S \circ \pi = f \circ \pi \circ T$$
  $\mu$  – almost everywhere.

Since T is ergodic, it follows that  $f \circ \pi$  is almost everywhere constant, and thus, f is almost

Let  $a \in [0,1)$  be irrational. The system  $(\mathbb{T}^2, \mathcal{B}_{\mathbb{T}^2}, m_{\mathbb{T}^2}, R_a \times R_a)$  is not ergodic, but the rotation by a is an ergodic factor of this system (the associated map is the projection on the first coordinate). To see that this system is not ergodic, consider the function f given by f(x,y) =x-y, and notice that this is a non-constant invariant function.

**P2.** Let G be a compact abelian group. Show that a group rotation by some  $\alpha \in G$  is ergodic if and only if  $\{n\alpha\}_{n\in\mathbb{Z}}$  is a dense subgroup of G.

**Hint:** You may use that any function in  $L^2(G)$  has a Fourier expansion  $f = \sum_{\chi} \widetilde{f}(\chi)\chi$  where convergence is understood to be in the  $L^2(G)$ -norm.

 $(\Longrightarrow)$  Suppose the rotation T by  $\alpha \in G$  is not dense in  $\{n\alpha\}_{n\in\mathbb{Z}}$ . Then there exists a nontrivial character  $\xi$  such that  $\xi(n\alpha) = 1$  for all  $n \in \mathbb{Z}$ . Indeed, consider  $H = \overline{\{n\alpha\}_{n \in \mathbb{Z}}}$  which is a compact strict subgroup of G. Consider the compact abelian group G/H and take any non-trivial character  $\tilde{\xi}$  in G/H. Then, define  $\xi(g) = \xi(g+H)$ . Clearly  $\xi(g) = 1$  for every  $g \in H, \xi$  is a morphism from G to  $\mathbb{S}^1$ , and it is continuous by being composition of continuous

Now take  $f = \xi$ . Then f is a non-constant, T-invariant function, and therefore T is not ergodic.

 $(\longleftarrow)$  If  $\{n\alpha\}_{n\in\mathbb{Z}}$  is dense in G, then for any non-trivial character  $\xi$ , we have  $\xi(\alpha)\neq 1$ . Let fbe a T-invariant function in  $L^2(G)$  and write its Fourier expansion

$$f = \sum_{\xi} c_{\xi} \xi.$$

$$\sum_{\xi} c_{\xi} \xi(\alpha) \xi = \sum_{\xi} c_{\xi} \xi.$$

By the uniqueness of the Fourier coefficients, we have  $c_{\xi}\xi(\alpha)=c_{\xi}$  for all  $\xi$ . Since  $\xi(\alpha)\neq 1$  for

all non-trivial  $\xi$ , it follows that  $c_{\xi} = 0$  for all  $\xi \neq 1$ . Then  $f \equiv c_1$  which is constant, and this shows that T is ergodic.

- **P3.** We call a system  $(X, \mathcal{B}, \mu, T)$  totally ergodic if for every  $k \in \mathbb{N}$  the map  $T^k$  is ergodic with respect to  $\mu$ .
  - (a) Show that if  $(X, \mathcal{B}, \mu, T)$  is totally ergodic, then for any  $a, b \in \mathbb{N}$  we have

$$\lim_{N \to +\infty} \left\| \frac{1}{N} \sum_{n=1}^{N} T^{an+b} f - \int f \, d\mu \right\|_{L^{2}(\mu)} = 0.$$

This is a simple application of von Neumann's ergodic theorem. Indeed, observe that  $T^{an+b}f = (T^a)^n(T^bf)$  and since the transformation  $T^a$  is ergodic, we deduce that (convergence here is in  $L^2$ -norm)

$$\frac{1}{N} \sum_{n=1}^{N} T^{an+b} f \to \int T^{b} f \ d\mu = \int f \ d\mu,$$

where the last equality follows from the fact that T preserves the measure  $\mu$ .

(b) Show that an ergodic system is totally ergodic if and only if every eigenfunction with corresponding eigenvalue that is a root of unity is constant almost everywhere.

Assume that a system is totally ergodic and let f be an eigenfunction with eigenvalue  $\lambda$  that is a root of unity. Thus, there exists  $r \in \mathbb{N}$  such that  $\lambda^r = 1$ . We conclude that

$$U_T^r f = U_T^{r-1}(\lambda f) = \dots = \lambda^r f = f.$$

Since  $T^r$  is ergodic, we conclude that f is constant almost everywhere.

For the converse direction, assume that the system is not totally ergodic. Therefore, there exists  $k \in \mathbb{N}$  and a non-constant function  $f \in L^2(X)$  for which  $U_T^k f = f$ .

If k = 1, we get that  $U_T f = f$ , which means that f is an eigenfunction (with eigenvalue 1). Therefore, f is constant almost everywhere, which is a contradiction. Therefore, we get  $k \geq 2$  and that T is ergodic.

Now, we suppose that  $k \geq 2$ . We consider the non-trivial roots of unity  $\omega_i = e(\frac{i}{k})$  where  $0 \leq i \leq k-1$  and define the functions

$$g_i = f + \omega_i U_T f + \dots + \omega_i^{k-1} U_T^{k-1} f.$$

Observe that, since  $U_T^k f = f$ , we have

$$U_T g_i = U_T f + \omega_i U_T^2 f + \dots + \omega_i^{k-1} f \implies U_T g_i = \frac{1}{\omega_i} g_i.$$

Therefore,  $g_i$  is an eigenfunction with eigenvalue a root of unity and our hypothesis implies that  $g_i$  is constant. In fact, for  $i \neq 0$  (that is,  $\omega_i \neq 1$ ), we get that since  $U_T g_i = \bar{\omega_i} g_i$ , the corresponding constant is zero and, hence,  $g_i = 0$  almost everywhere.

We sum the functions  $g_i$  for  $0 \le i \le k-1$  and deduce that

$$\sum_{i=0}^{k-1} \sum_{r=0}^{k-1} e\left(\frac{ri}{k}\right) U_T^r f$$

is constant almost everywhere. Changing the order of summation, we have

$$\sum_{r=0}^{k-1} U_T^r f\left(\sum_{i=0}^{k-1} e\left(\frac{ri}{k}\right)\right) = C \quad m - \text{a.e.}$$

for some constant C. Notice that

$$\sum_{i=0}^{k-1} e\left(\frac{ri}{k}\right) = \begin{cases} k, & \text{if } r=0\\ 0, & \text{if } r\neq0 \end{cases}.$$

Namely, all the terms in the last sum disappear, apart from the term with r = 0. We conclude that kf = C almost everywhere and thus f is a constant function, which is a contradiction. We conclude that the system is totally ergodic.

**P4.** (a) Let  $(X, \mathcal{B}, \mu, T)$  be an ergodic measure preserving system, and let  $\alpha \in (0, 1)$  such that  $e(\alpha)$  is an eigenvalue. Show that there exists a non-trivial group rotation that is a factor of  $(X, \mathcal{B}, \mu, T)$ .

**Hint:** When a = r/q is rational (with q minimal among all such rational eigenvalues), construct a  $T^q$ -invariant set B such that  $\mu(B) = 1/q$ .

Let  $f \in L^2(X)$  be the eigenfunction corresponding to the given eigenvalue. Then  $Tf = e(\alpha)f$  and f is non-constant.

Suppose first that  $\alpha \in \mathbb{Q}$ . We write  $\alpha = r/q$  for some 0 < r < q with (r,q) = 1. Then  $T^q f = f$  and thus the transformation  $T^q$  is not ergodic. Let  $q \geq 2$  be the minimal integer (larger than 1) for which  $T^q$  is not ergodic and consider  $A \in \mathcal{B}$  such that  $T^{-q}A = A$  and  $\mu(A) \in (0,1)$ .

Define  $g = \sum_{n=0}^{q-1} T^n \mathbb{1}_A$  and notice that g is T-invariant. It follows by ergodicity that g is almost everywhere equal to some integer constant, and then  $q\mu(A) = \int g d\mu \in \mathbb{Z}$ . Thus,  $\mu(A) = k/q$  for some  $k \in \{1, \ldots, q-1\}$ .

<u>Claim</u>. There exists a  $T^q$ -invariant set  $B \in \mathcal{B}$  such that  $\mu(B) = 1/q$ .

To prove the claim, suppose that k>1, since otherwise the claim holds trivially. First, we notice that by the pigeonhole principle, there exists some  $m\in\{1,\ldots,q-1\}$  such that  $\mu(A_1)>0$ , where  $A_1=A\cap T^{-m}A$ . If  $\mu(A_1)=\mu(A)$ , then  $T^{-m}A=A$  almost everywhere, which contradicts the minimality of q. Then  $0<\mu(A_1)<\mu(A)=k/q$ . We can define  $g_1$  as we defined g substituting A with  $A_1$ , and since  $A_1$  is also  $T^q$ -invariant, then as before, there exists some integer  $0< k_1 < k$  such that  $\mu(A_1)=k_1/q$ . If  $k_1=1$ , then the claim follows by taking  $B=A_1$ . Otherwise we repeat the same argument for  $A_1$  instead of A, to find some set  $A_2$  with  $\mu(A_2)=k_2/q$  for some  $0< k_2 < k_1$ . Inductively, we find  $j\in\{1,\ldots,q-1\}$  such that  $B=A_j$  satisfies the claim.

Now, consider the set  $Y = \{0, \ldots, q-1\}$ , let  $\mathcal{B}_Y$  be the discrete  $\sigma$ -algebra on Y,  $\nu$  be the normalized counting measure on Y, and let  $S: y \mapsto y+1 \pmod{q}$ . Then  $(Y, \mathcal{B}_Y, \nu, S)$  is a measure-preserving system (a rotation on finitely many points). Using our claim, we deduce that the sets  $B, T^{-1}B, \ldots, T^{q-1}B$  form a partition of X, thus for any  $x \in X$ , there exists a unique  $y_x \in Y$  such that  $x \in T^{-y_x}B$ . We can then define the map  $\pi: X \to Y$  by  $\pi(x) = y_x$ , and it is not hard to check that this is a factor map.

Now suppose that  $\alpha \notin \mathbb{Q}$ . We show that  $(\mathbb{T}, \mathcal{B}_{\mathbb{T}}, m_{\mathbb{T}}, R_{\alpha})$  is a factor of  $(X, \mathcal{B}, \mu, T)$ . We identify  $\mathbb{T}$  with [0,1) for simplicity. Let  $\pi: X \to \mathbb{T}$  be the map defined uniquely by the equality  $f(x) = e(\pi(x))$ . Observe that this is well-defined for almost all  $x \in X$ , since |f(x)| = 1 almost everywhere.

We observe that

$$e(\pi(Tx)) = f(Tx) = e(\alpha)f(x) = e(\pi(x) + \alpha) = e(R_{\alpha}\pi(x)),$$

which means that  $\pi(Tx) = R_a\pi(x)$  almost everywhere. Finally,  $\pi$  preserves  $m_{\mathbb{T}}$ . To see this, define a measure  $\nu$  on  $\mathbb{T}$  by  $\nu(A) = \mu(\pi^{-1}A)$ ,  $A \in \mathcal{B}$ . We easily check that  $\nu$  is  $R_{\alpha}$ -invariant, and so it is the Haar measure  $m_{\mathbb{T}}$  (the only measure invariant under an irrational rotation is the Haar measure).

(b) Show that given any countable subgroup  $K \leq \mathbb{S}^1$ , there exists a measure preserving system  $(X, \mathcal{B}, \mu, T)$  on a Borel probability space such that K is the point-spectrum of T.

**Hint:** To construct the system take  $X = \hat{K}$ ,  $\mu = m_X$  the normalized Haar measure on X, and T to be some appropriate group rotation.

Give K the discrete topology, so that the dual group  $\hat{K}$  is a compact metric abelian group. Following the hint, we take  $X = \hat{K}$ ,  $\mu = m_X$  the normalized Haar measure on X. Define the character  $\theta \in X$  by  $\theta(k) = k$ , for  $k \in K$ . Define the transformation  $T: X \to X$  to be the rotation by  $\theta$ . In this way,  $(X, \mathcal{B}, \mu, T)$  is a measure-preserving system. We need to show that such a system has point-spectrum K.

First, we see that  $K \leq spec(T)$ . Indeed, we recall that Pontryagin's Theorem yields that K is isomorphic to  $\hat{X}$  given by  $k \to f_k$  where  $f_k(x) = x(k)$ . Therefore, for any character  $f_k \in \hat{X}$  and  $x \in X$ 

$$(U_T f_k)(x) = f_k(\theta x) = f_k(\theta) f_k(x) = \theta(k) f_k(x) = k f_k(x).$$

Thus  $f_k$  is an eigenfunction of  $U_T$  with eigenvalue k, and hence  $K \leq spec(T)$ .

To prove the other direction, recall that for any compact abelian group G we have that  $\hat{G}$  is a orthonormal basis for  $L^2(G)$ . This means that if f is an eigenfunction of  $U_T$  with eigenvalue  $\lambda$ , then

$$f = \sum_{k \in K} c_k f_k,$$

where  $c_k \in \mathbb{C}$  and the equality is in  $L^2(X)$ . Applying  $U_T$  and using the uniqueness of the coefficients, we have that

$$kc_k = \lambda c_k$$

for every  $k \in K$ . Thus  $c_k = 0$  unless  $k = \lambda$ , and therefore  $f = c_{\lambda} f_{\lambda}$ . Therefore  $spec(T) \leq K$  since K is isomorphic to  $\hat{X}$ .